

### Y13 Pure Chapter 12—Vectors



#### What do I need to be able to do?

By the end of this chapter you should be able to:

- Understand 3D Cartesian coordinates
- Use vectors in three dimensions
- Use vectors to solve geometric problems
- Model 3D motion in mechanics with vectors

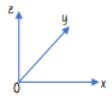
## Key words:

Coplanar vectors — Vectors in the same plane

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Magnitude— The size of the vector

### 3D Coordinates



When visualising 3D coordinates, think of the x and y axis drawn on a flat surface with the z axis sticking up from the flat surface.

The distance from the origin to the point (x, y, z) is:  $\sqrt{x^2 + y^2 + z^2}$ 

The distance between the points  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$ 

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$$\sqrt{(x_1-x_2)^2+(y_1-y_2)^2+(z_1-z_2)^2}$$

# 3D Vectors

Unit vectors along the x, y and z axes are denoted by l, j and k respectively

$$i = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} j = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \ k = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

For any 3D vector  $p\mathbf{i} + q\mathbf{j} + r\mathbf{k} = p$ 

 $\binom{p}{q}$ 

## Parallel Vectors in 3D

If a, b, and c are 3D, non-coplanar vectors (not in the same plane) then you can compare coefficients on both sides of an equation:

$$p\mathbf{i} + q\mathbf{j} + r\mathbf{k} = u\mathbf{i} + v\mathbf{j} + w\mathbf{k}$$

Then: p=u, q=v and r=w

### Magnitude and Direction

Vector  $a = p\mathbf{i} + q\mathbf{j} + r\mathbf{k}$ 

Magnitude of vector a:

$$|\boldsymbol{a}| = \sqrt{p^2 + q^2 + r^2}$$

Direction of vector a:

The angle with the x-axis:  $\cos \theta_x = \frac{p}{|a|}$ 

The angle with the y-axis:  $\cos \theta_y = \frac{q}{|a|}$ 

The angle with the z-axis:  $\cos \theta_z = \frac{r}{|a|}$ 

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